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Abstract

An experiment is reported which tests whether network information is more effectively displayed in a three dimensional space than in a two dimensional space. The experimental task is to trace a path in a network and the experiment is carried out in 2D, in a 3D stereo view, in a 3D view with head coupled perspective, and in a 3D stereo view with head coupled perspective; this last condition creates a localized virtual reality display. The results show that the motion parallax obtained from the head coupling of perspective is more important than stereopsis in revealing structural information. Overall the results show that three times as much information can be perceived in the head coupled stereo view as in the 2D view.

1. Introduction

As the display of three dimensional rather than two dimensional information becomes commonplace due to advances in computer graphics hardware, the development of visual languages and symbologies that work in 3D will become increasingly important. One of the outstanding issues is the question of whether there is any advantage to creating visual languages that are truly three dimensional since the information is typically not spatial in nature. The present study addresses this issue by empirically testing the comprehension of network information shown in 3D and in 2D.

A useful and interesting method for examining three dimensional structures is to couple a perspective stereoscopic view of a 3D scene to the user's eye positions and update the view in real-time as the user moves. The key elements of this are a high resolution monitor capable of running at a high frame rate, stereo glasses and some method for tracking the user's head position [1,2]. The position of the user's two eyes are computed from the head position and separate images are generated showing the correct perspective view of a set of virtual objects somewhere in the vicinity of the monitor screen. The result is a localized "Virtual Reality" (VR) environment which has a number of advantages over the much talked about immersive virtual reality, not the least of these being that the everyday workspace of desk, filing cabinet, co-workers and coffee mug are not excluded. In our previous work we have called this "Fish Tank VR" to characterize its localized nature and distinguish it from the full immersion kind [4].

2. Experiment

While it is clear that the kind of 3D display described above has advantages for people who wish to look at representations of 3D data, such as images of bones used for planning orthopaedic surgery, it is not clear that abstract data can benefit from 3D representation. The key question is, is a 3D diagram better than a 2D diagram? Some previous studies have suggested that there is and advantage but say nothing about *how large* the advantage is [1,3].

The purpose of this experiment was to determine how much more, or less, can be perceived in a head coupled stereo display used to display network information. On a given trial the subject viewed a randomly laid out network of nodes and arcs with two nodes highlighted. The task was to say if there was a path between the the the highlighted nodes, while in fact there was either a path of length two or no path, each occurring 50% of the time. There were four viewing modes.

1) **2D:** no stereo, no rotation; the 3D graph was projected onto a 2D plane using an orthographic (parallel) projection by removing Z axis information, hence no overlap information was available.

2) **Stereo perspective:** no rotation; this condition made use of a pair of StereoGraphics CrystalEyes LCD shutter glasses to provide the disparity depth cues.

3) **Head coupled perspective:** the scene's perspective projection changed continuously according to the subject's measured head position; the perspective projection was defined by a single viewpoint centered between the eyes.

4) **Stereo, head coupled perspective:** same as above, except with stereo; the correct view was generated for each eye position (continuously updated).

The numbers of nodes used in the different conditions were as follows; these had been established as useful ranges in a previous pilot study.

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1) 21, 42, 63, 84, 105
2) 51, 81, 111, 141, 171
3) 81, 117, 153, 189, 225
4) 111, 156, 201, 249, 291

The number of arcs was the number of nodes multiply by 4/3.

This experiment involved 11 participants. (The other procedure details are given in a technical report [5].)

3. Results and discussion

Figure 1 summarizes the error data from this experiment. This figure shows a sequence of curves with varying gradients which appear to be roughly multipliers of each other with respect to the graph size. That is, error rate appears to be directly proportional to the number of nodes, with a different gradient for the different conditions. To test this model we fitted a set of straight lines through the data with a zero intercept. These are shown as the broad lines running through the sets of points in Figure 4. Note that the vertical bars represent one standard error and that the true mean should lie outside of the range of two standard errors approximately five percent of the time. This very simple model appears to be a reasonable first approximation to the data, although as the errors approach 40% there appears to be some flattening of the curves.

On the basis of these results we conclude that the graph that can be understood with head coupled stereo is about

3.0 times as large as the 2D graph for any given error rate (taking the ratios of the gradients). Using stereo alone appears to increase the comprehensible graph size by approximately a factor of 1.6 and using head coupling alone appears to increase the comprehensible graph size by a factor of 2.2.

Many visual languages are networks of nodes connected by arcs. Because of the advantage of 3D viewing over 2D viewing, we can confidently predict that as high performance 3D graphics systems become commonplace, many visual languages will evolve from a 2D to a 3D layout. However, many challenging design problems will have to be solved in order to create symbology that works well in 3D.

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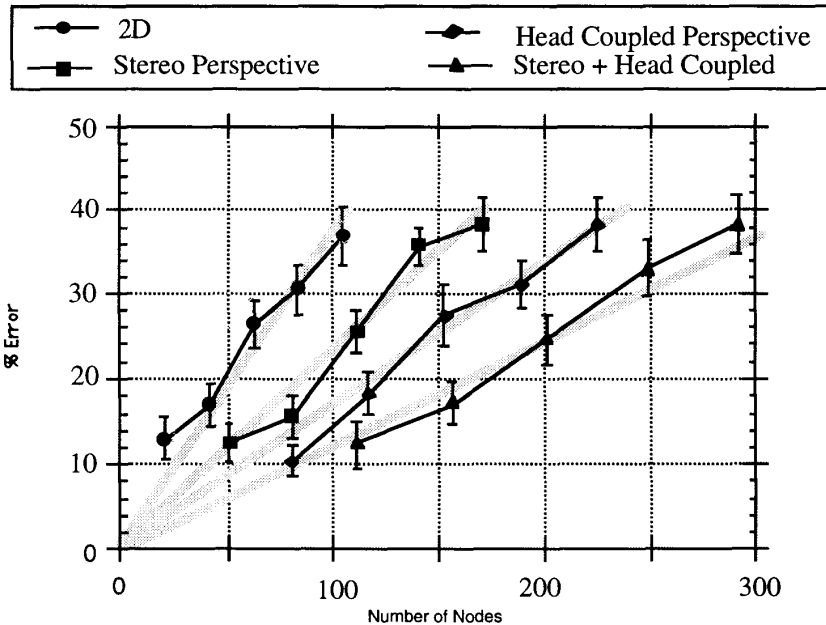
Figure 1. Error data from Experiments 1a and 1b. Vertical bars represent one standard error of the mean. The straight lines represent the simple model described in the text.